

The information-disturbance tradeoff describes the inevitable disturbance caused to a quantum system when information is gained through a measurement. It can be cast as a special case of a more general problem, in which we consider the problem of approximate simultaneous realisations of two arbitrary (and not necessary compatible) quantum operations. In general this leads to a trade-off where increasing quality of one operation necessarily decreases the quality of the other. We prove that a tight trade-off bound on the quality of the two approximate simultaneous realisations (when measured in terms of the cb norm) can be computed in terms of a semi-definite program (SDP). For the special case of the information-disturbance tradeoff, the resulting SDP allows us to obtain analytic results for binary von Neumann measurements.

## Setting and distance measures

Consider systems on a finite dimensional Hilbert space  $\mathcal{H} = \mathbb{C}^d$ .

**Quantum state** Every quantum state is described by a density matrix  $\rho \in \mathcal{M}_d$  with  $\text{Tr}[\rho] = 1$  and  $\rho \geq 0$ .

**Quantum channel** A transformation of a quantum state is described by a quantum channel, which is a linear completely positive trace preserving map

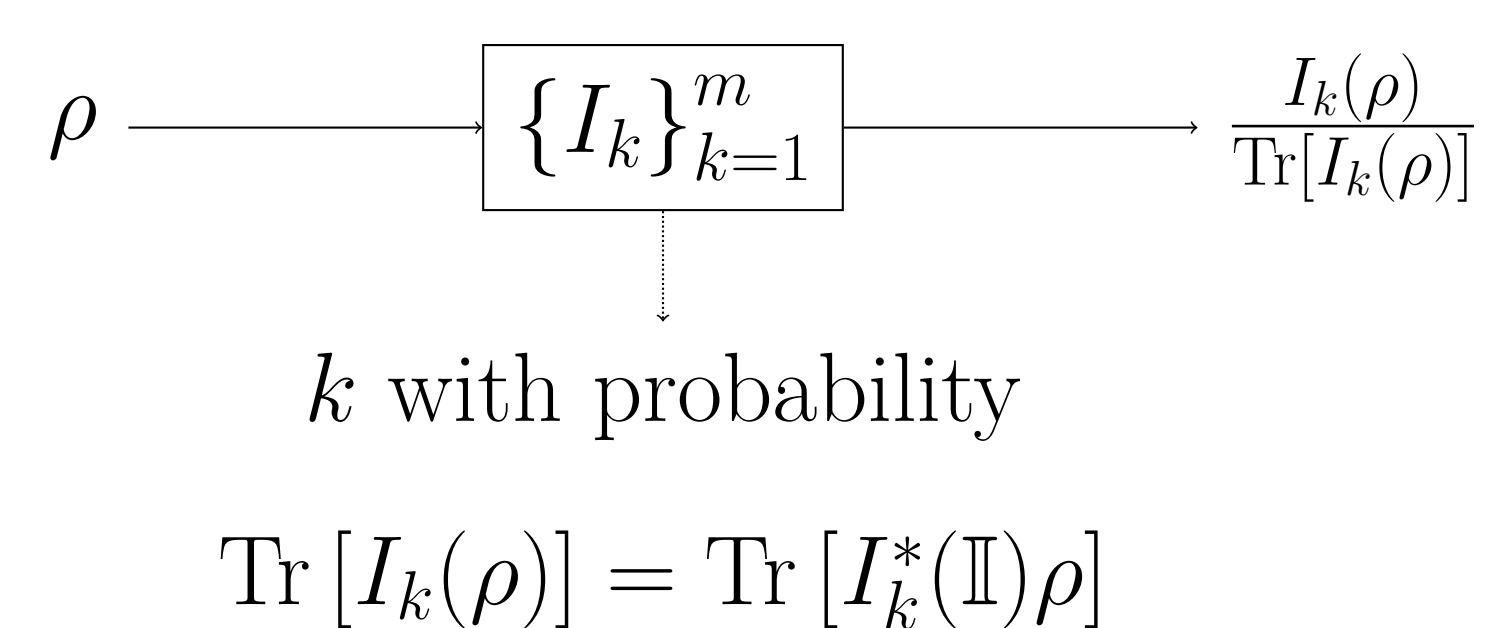
$$T : \mathcal{M}_d \rightarrow \mathcal{M}_{d'}.$$

**POVM** A discrete observable  $\mathcal{P}$  is described by a positive-operator valued measure (POVM), characterised by positive operators

$$\begin{aligned} \mathcal{P} &:= \{P_k \in \mathcal{M}_d\}_{k=1}^m, \text{ satisfying} \\ 0 &\leq P_k \leq \mathbb{I} \quad \forall k \text{ and} \\ \sum_{k=1}^m P_k &= \mathbb{I}. \end{aligned}$$

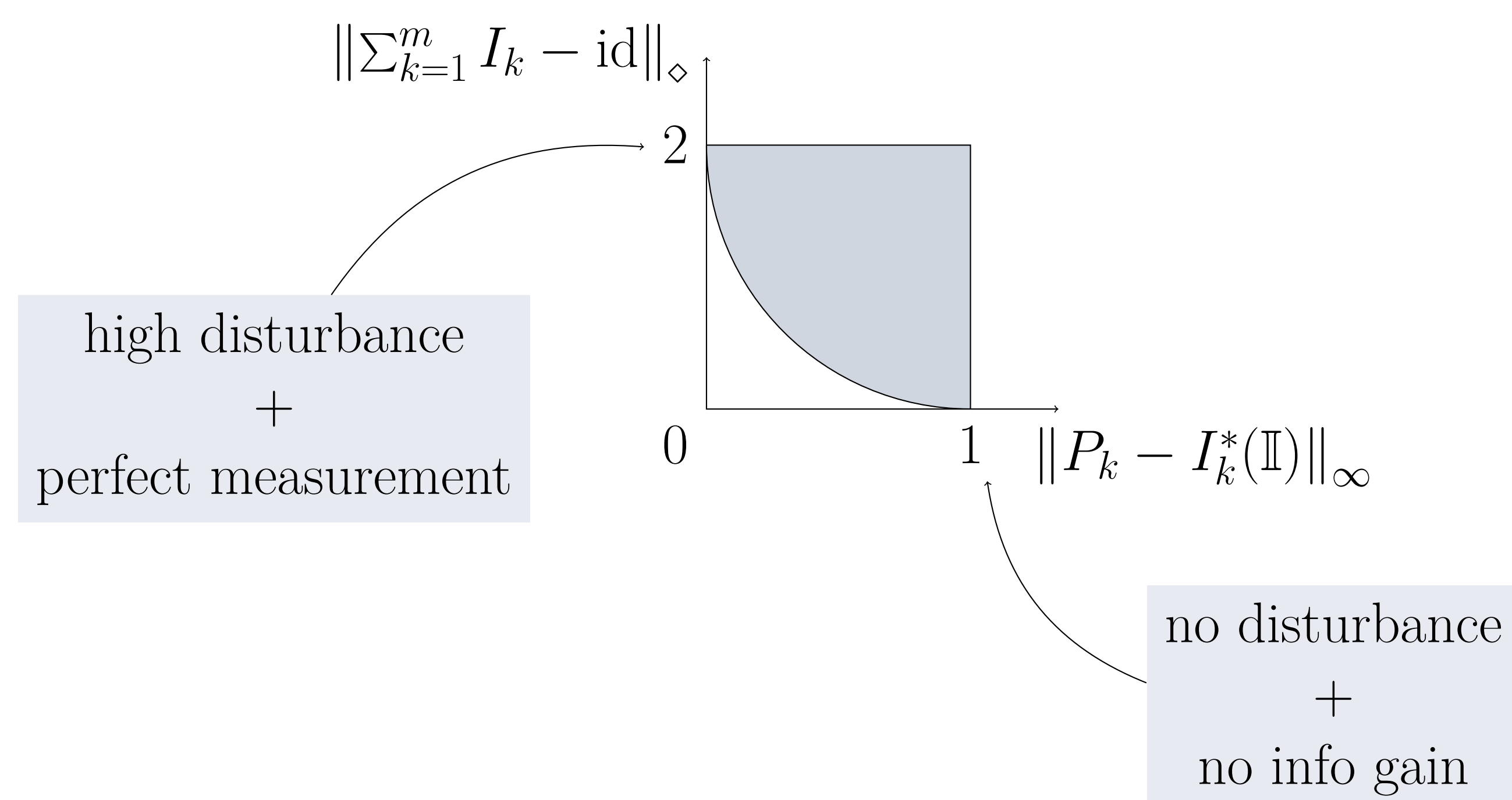
**Instrument** A general measurement scheme is represented by an instrument  $\mathcal{I}$ , which is characterised by completely positive linear maps

$$\mathcal{I} := \{I_k : \mathcal{M}_d \rightarrow \mathcal{M}_{d'}\}_{k=1}^m, \text{ satisfying} \\ \sum_{k=1}^m I_k^*(\mathbb{I}) = \mathbb{I}.$$



An instrument therefore comprises a quantum channel and a POVM. If we ignore the measurement outcome, the instrument  $\mathcal{I}$  acts as a quantum channel,  $\sum_k I_k$ . If we ignore the quantum state of the output, the instrument  $\mathcal{I}$  acts as a POVM,  $\{I_k^*(\mathbb{I})\}$ .

The goal of this project is to completely characterise the set of all achievable information disturbance combinations and thus determine its boundary, the information-disturbance tradeoff.



Fix a POVM  $\mathcal{P} := \{P_k\}_{k=1}^m$  and consider an instrument  $\mathcal{I} := \{I_k\}_{k=1}^m$ .

① The distance measure quantifying the information gained from the quantum system when performing the measurement  $\{I_k^*(\mathbb{I})\}$ , in comparison to the measurement  $\{P_k\}$  is

$$d_1(P_k, I_k^*(\mathbb{I})) = \sup_{\rho} |\text{Tr}[\rho P_k] - \text{Tr}[I_k^*(\mathbb{I})\rho]| = \|P_k - I_k^*(\mathbb{I})\|_{\infty} \quad \forall k.$$

This is the worst case over all quantum states  $\rho$  of the difference of the probabilities for a specific measurement outcome  $k$  to occur regarding the measurements  $\{P_k\}$  and  $\{I_k^*(\mathbb{I})\}$ .

② The distance measure quantifying the disturbance caused to the quantum system  $\sum_k I_k$  in comparison to the identity channel  $\text{id}$  is

$$d_2\left(\sum_{k=1}^m I_k, \text{id}\right) = \sup_{\rho} \left\| \sum_{k=1}^m I_k \otimes \text{id}(\rho) - \text{id}(\rho) \right\|_1 = \left\| \sum_{k=1}^m I_k - \text{id} \right\|_{\diamond}.$$

We compare the pre-measurement quantum state to the post-measurement quantum state.

## Optimisation problem

### Task ( $\star$ )

Compute for a given POVM  $\mathcal{P}$  and  $\lambda \in [0, 1]$ :

$$\begin{aligned} \min & \left\| \text{id} - \sum_{k=1}^m I_k \right\|_{\diamond} \\ \text{s.t.} & \|I_k^*(\mathbb{I}) - P_k\|_{\infty} \leq \lambda \quad \forall k, \\ & I_k \text{ is c.p. and} \\ & \sum_{k=1}^m I_k^*(\mathbb{I}) = \mathbb{I} \quad \forall k. \end{aligned}$$

## Results

### Theorem ( $\star$ )

For a given POVM  $\mathcal{P}$  and  $\lambda \in [0, 1]$ , the optimisation specified in Task ( $\star$ ) can be formulated as an SDP  $(\phi, C, D)$ , where  $\phi : \mathcal{M}_d \rightarrow \mathcal{M}_{d'}$  is a hermiticity preserving map,  $C = C^* \in \mathcal{M}_d$  and  $D = D^* \in \mathcal{M}_{d'}$ , with the primal and the dual SDP problem given as follows

$$\begin{aligned} \max & \text{Tr}[CX] \\ \text{s.t.} & \phi(X) = D \\ & X \geq 0 \end{aligned} \quad \stackrel{\text{Slater-type strong duality holds}}{=} \quad \begin{aligned} \min & \text{Tr}[DY] \\ \text{s.t.} & \phi^*(Y) \geq C \\ & Y = Y^* \end{aligned}$$

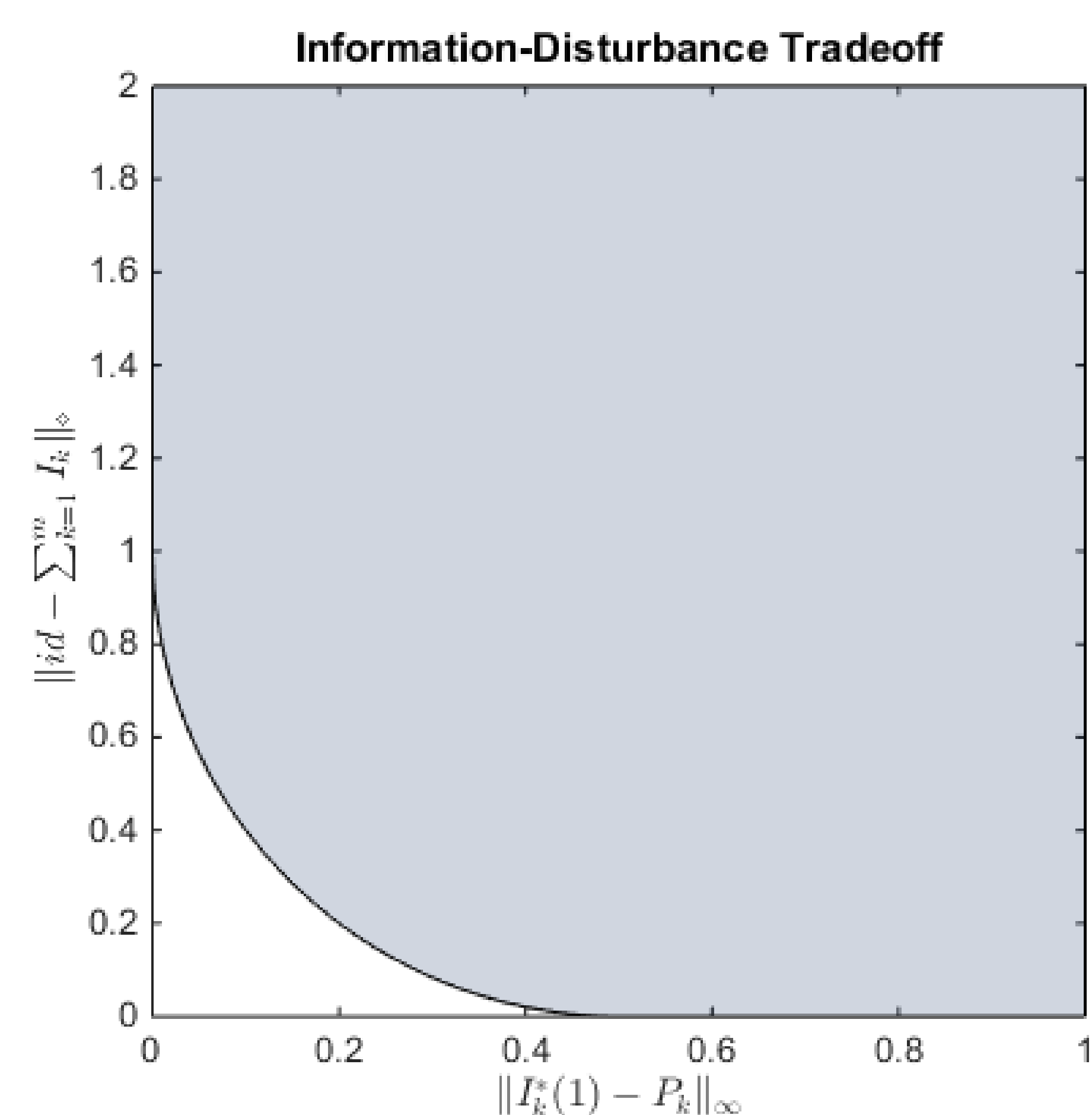


Figure 1: The set of achievable information disturbance combinations for a fixed binary von Neumann measurement  $\mathcal{P} = \{P, \mathbb{I} - P\}$ . The information-disturbance tradeoff is given by an ellipse

$$d_2\left(\sum_{k=1}^m I_k, \text{id}\right) \geq 1 - 2\sqrt{d_1(P_k, I_k^*(\mathbb{I})) - (d_1(P_k, I_k^*(\mathbb{I})))^2}.$$

## Literature

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